

Last time:
- Majorization-minimization based algo.
- Reweighted ℓ_1 and ℓ_2 methods.

Today:
- Analysis of reweighting based methods
(properties of local minima).

Recap: separable set fn:

$$\min_{x \in \mathbb{R}^n} \sum_{i=1}^m g_i(x_i) \text{ s.t. } Ax = y$$

Examples: $g(x) = |x|^p, 0 < p < 1$
 $g(x) = \lambda |x|$
 $g(x) = |x + \beta|^p, 0 < p < 1$
 $g(x) = \lambda |x + \beta|, \text{ etc.}$

Reweighted ℓ_2 methods:

Consider $g(x) = \lambda \|x\|_2^2$ if x is still nonzero in \bar{S} , upper bound $g(x)$ as a linear fn. of \bar{y} via the 1st order Taylor expansion \rightarrow quadratic in x .

$$x^{(k+1)} \leftarrow \arg \min_{x \in \mathbb{R}^n} \|y - Ax\|_2^2 + \lambda \sum_{i \in \bar{S}} w_i^k |x_i|^2$$

$$\Rightarrow x^{(k+1)} = W_k (A^T A W_k + \lambda I)^{-1} A^T y$$

The matrix inversion lemma:

$$x^{(k+1)} = W_k^T A^T (A W_k^T A^T + \lambda I)^{-1} y$$

E.g., with $g(x) = |x|^p, 0 < p < 1$,
 $W_k^i = \text{diag} \{ |x_i^{(k)}|^{p-2} \}$

with $g(x) = (|x + \beta|^p), 0 < p < 1, \beta > 0$,
 $W_k^i = \text{diag} \{ (|x_i^{(k)} + \beta|^{p-2}) \}$

Reweighted ℓ_1 min:

Here we bound $g(x)$, $g(x) \geq 0$ as a fn. of x , not x^2 , and also

$$x^{(k+1)} \leftarrow \arg \min_{x \in \mathbb{R}^n} \|Ax - y\|_1 + \lambda \sum_{i \in \bar{S}} w_i^k |x_i|$$

E.g., with $g(x) = |x|^p, 0 < p < 1$,
 $W_k^i = \text{diag} \{ |x_i^{(k)}|^{p-1} \}$

with $g(x) = (|x + \beta|^p), 0 < p < 1, \beta > 0$,
 $W_k^i = \text{diag} \{ |x_i^{(k)} + \beta|^{p-1} \}$

Other $g(x)$: as long as it is convex, same approach works.

only need $g'(x)$.
 e.g. $g(x) = \lambda |x|$.

Weighted ℓ_1 version:
 $g(x) = \lambda |x| \leq \frac{1}{2} \lambda x^2 \leq \frac{1}{2} \lambda (x^2 + \beta^2), \beta > 0$

convex in y : (check!)
 $\lambda (|x + \beta|) \leq \frac{\lambda}{2} (x + \beta)^2 + \lambda \frac{\beta^2}{2}$

We thus get the iteration w/ up:
 $x^{(k+1)} \leftarrow \arg \min_{x \in \mathbb{R}^n} \|Ax - y\|_1 + \lambda \sum_{i \in \bar{S}} \frac{x_i^2}{(x_i^{(k)} + \beta)^2}$ [Chaffard]

(Weighted ℓ_2 problem).

Weighted ℓ_1 version: $g(x) = \lambda |x| \leq \frac{1}{2} \lambda (x + \beta)^2$, $\beta > 0$

And we get the iteration:
 $x^{(k+1)} \leftarrow \arg \min_{x \in \mathbb{R}^n} \|Ax - y\|_1 + \lambda \sum_{i \in \bar{S}} \frac{|x_i|}{(x_i^{(k)} + \beta)}$ [Candès, Wain, Boyd]

Local minima of $g(x) = \sum_{i=1}^m |x_i|^p$ s.t. $Ax = y$:

Let x_0 be a feasible point of interest, i.e., $Ax_0 = y$.
 In our case: local minima candidates, i.e., basic feasible solns.

Consider a feasible pt. $x_0 + \epsilon z, \epsilon > 0, z \in N(x_0), A(x_0 + \epsilon z) = y$.
 Let $h(\epsilon) \triangleq g(x_0 + \epsilon z)$; $h(0) = g(x_0)$.

Want to examine $h(\epsilon)$ when $\epsilon_i \rightarrow \pm \infty$.

If $h(\epsilon) > h(0)$ for some sufficiently small $\epsilon, \epsilon \neq 0 \in N(x_0)$, then x_0 is a local min.

So we compute $\frac{dh(\epsilon)}{d\epsilon}$ and see if it is positive.

$$\frac{dh(\epsilon)}{d\epsilon} = \sum_{i=1}^m \frac{\partial g(x_0 + \epsilon z)}{\partial x_i} \cdot \frac{\partial (x_0 + \epsilon z)_i}{\partial \epsilon}$$

$$= \sum_{i=1}^m \frac{\partial g(x_0 + \epsilon z)}{\partial x_i} (z_i)$$

(use $\frac{\partial |x|^p}{\partial x} = p|x|^{p-1} \frac{x}{|x|}$)

WLOG, assume the first m entries of z_0 are nonzero.

$$\frac{dh(\epsilon)}{d\epsilon} = \sum_{i=1}^m \frac{\partial g(x_0 + \epsilon z)}{\partial x_i} (z_i) + \sum_{i=m+1}^n \frac{\partial g(x_0 + \epsilon z)}{\partial x_i} (z_i)$$

$$= T_1 + T_2$$

As $\epsilon \rightarrow 0, T_1 \rightarrow$ some constant (see ex 10)

$$T_1 = \sum_{i=1}^m \frac{\partial g(x_0)}{\partial x_i} (z_i)$$

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Some remarks on reweighted ℓ_1 vs. reweighted ℓ_2 :

- Each iteration of ℓ_1 reweighting is more computationally expensive than reweighted ℓ_2 (closed form updates).
 - But # iterations of reweighted ℓ_1 typically \ll # iterations of reweighted ℓ_2 .
 - With reweighted ℓ_1 , even ± 1 \Rightarrow sparse soln. (unlike reweighted ℓ_2).
- Typically, much easier to incorporate additional constraints (non-negativity, box constraints, etc.) of reweighted ℓ_1 .
 Reweighted ℓ_2 \Rightarrow no longer have closed-form solns.
- Can consider other ways to bound besides ℓ_1 or ℓ_2 ; as long as the bounding fn. is convex, each step gives a convex opt. pt.
 $\ell_1 \Rightarrow$ closed form updates
 $\ell_2 \Rightarrow$ each iteration promotes sparsity
- The choice of $w_i^{(k)}$ is determined by the surrogate cost fn. for promoting sparsity that is being minimized.
 - Different surrogate fns. lead to different alphas with different performance-complexity tradeoffs.

[Chartrand and Yin] Reweighted ℓ_2

$$g(x) = (x^2 + \beta)^{1/2}$$

$$h(\tilde{y}) = (\tilde{y} + \rho)^{1/2}, \quad \tilde{y} \geq 0$$

$$h'(\tilde{y}) = \frac{1}{2} (\tilde{y} + \rho)^{-1/2}, \quad h''(\tilde{y}) = -\frac{1}{4} (\tilde{y} + \rho)^{-3/2} < 0$$

$$h(\tilde{y}) \leq h'(\tilde{y}) (\tilde{y} - \tilde{y}_0) + h(\tilde{y}_0)$$

$$z^{(k+1)} = \arg \min_{z \in \mathbb{R}^n} \|Ax - y\|_2^2 + \lambda \sum_{i=1}^m \left(h'(\tilde{y}_i) \right)_{z_i}^2$$

$$= \arg \min_{z \in \mathbb{R}^n} \|Ax - y\|_2^2 + \lambda \sum_{i=1}^m \underbrace{\left((x_i^{(k)} + \rho)^{-1/2} \right)_{z_i}^2}_{w_i^{(k)}}$$

$$w_i^{-2} = \text{diag} \left\{ \left((x_i^{(k)} + \rho)^{-1/2} \right)_{z_i}^2 \right\}$$

\Rightarrow Reweighted ℓ_2 based method.

$$\text{Let } w_i^{(k)} = \left((x_i^{(k)} + \rho)^{-1/2} \right)_{z_i}^2$$

When $\rho \rightarrow \infty$, Chartrand-Yin updates:

$$w_i^{(k)} = \left((x_i^{(k)} + \rho)^{-1/2} \right)_{z_i}^2$$

When $\rho \rightarrow 0$, Focuss: $\rho = 2$

$$w_i^{(k)} = \left(x_i^{(k)} \right)_{z_i}^2$$

When $\rho = 1$, (Recall: $\min_{x \in \mathbb{R}^n} \sum_{i=1}^m (x_i + \rho)^{1/2}$, s.t. $Ax = y$)

$$\left(\text{As } \rho \rightarrow 0 \text{ and } \rho \rightarrow \infty, \min_{x \in \mathbb{R}^n} \sum_{i=1}^m |x_i| \text{ s.t. } Ax = y, \lambda_1 \text{ min.} \right)$$

$$w_i^{(k)} = \left((x_i^{(k)} + \rho)^{-1/2} \right)_{z_i}^2$$

\Rightarrow A more robust iterative method to (P_1) .

As $\rho \rightarrow 0$, we are trying to solve

$$\min_{x \in \mathbb{R}^n} \|Ax - y\|_2^2 + \lambda \sum_{i=1}^m |x_i|$$

\Rightarrow Intuitive explanation of why the Chartrand-Yin updates yield sparse solutions.